

# ALOHA

WidowX Leader Arm



## FEATURES

**6 Degrees of Freedom (DoF)**

**650mm Reach**

**1300mm Span**

**1mm Repeatability**

**5-8mm Accuracy**

## UPGRADED HAPTICS AND JOINTS

- Compression-proof bearings with no risk of over tightening or wearing out over thousands of hours of use
- Dual industrial-grade rails and carriages
- New, easily swappable 3D-printed ergonomic handles and finger paddles with universal mounting brackets for support of custom handles and finger paddles.
- New all-metal bracket joints

## Easily Repairable

The X-Series arms are made for the lab, our arms are intended to be worked on and we've made it as easy as possible to keep your manipulator up and running. Quickly and easily swap out motors that need to be replaced, lengthen or shorten the arm to your needs. Everything you need to repair your platform is kept in stock, making it easy to keep your equipment up and running with minimal downtime.

## POWERED BY INTERBOTIX

Aloha Kits are powered by our Interbotix Python library. Cut hundreds of lines of code down to a dozen or so, and take the guess work out of low level CAN programming by using our simple and intuitive modules.



[Learn More About Interbotix](#)

[TrossenRobotics.com/WidowX-Aloha-Set](https://TrossenRobotics.com/WidowX-Aloha-Set)

Interested in the Aloha WidowX Leader Arms? Contact our sales team: [Sales@TrossenRobotics.com](mailto:Sales@TrossenRobotics.com)



# ALOHA WidowX Leader Arm

## SPECIFICATIONS

<b>Degrees of Freedom</b>	6 Degrees
<b>Reach</b>	650mm
<b>Span</b>	1300mm
<b>Repeatability</b>	1mm
<b>Accuracy</b>	5-8mm
<b>Working Payload</b>	N/A to Leader Arm
<b>Interbotix</b>	✓
<b>Works with ROS 1/2</b>	✓
<b>Works with MoveIt</b>	✓
<b>Works with Gazebo</b>	✓
<b>Works with Python-ROS</b>	✓
<b>Servos</b>	7X XM430-W350-T   2X XL430-W250-T
<b>Communication Hub</b>	DYNAMIXEL U2D2
<b>Power Supply</b>	12 Volt - 5 Amp
<b>Tools and Bolts</b>	All Included
<b>Wrist Rotate</b>	Yes
<b>Weight</b>	3.8kg / 8.37lbs

# ALOHA WidowX Leader Arm

## TECHNICAL DRAWING

